



# Sequential Detection of Changes: an overview

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## Outline

- ★ Sequential hypothesis testing and Sequential detection of changes
- ★ The Sequential Probability Ratio Test (SPRT) for optimum hypothesis testing
- ★ Performance criteria and optimum detection rules for sequential change detection
- ★ Lorden's criterion and the CUSUM test
- ★ Course-Layout

# Sequential Hypothesis testing

In conventional (fixed sample size) binary hypothesis testing we are given a collection of observations  $\xi_1, \dots, \xi_t$  that satisfy one of the following two hypotheses


$$H_0: \xi_1, \dots, \xi_t \sim \mathbb{P}_0$$

$$H_1: \xi_1, \dots, \xi_t \sim \mathbb{P}_1$$

Using the available information (observations) we would like to decide which hypothesis is valid. This is achieved with the help of a

**Decision rule**  $D(\xi_1, \dots, \xi_t) \in \{0, 1\}$

$$u_t = \log \left( \frac{d\mathbb{P}_1}{d\mathbb{P}_0}(\xi_1, \dots, \xi_t) \right) \begin{matrix} H_1 \\ \geq \\ t \\ \leq \\ H_0 \end{matrix}$$



In sequential hypothesis testing observations  $\xi_1, \dots, \xi_t, \dots$  are supplied **sequentially**. With every new time instant we obtain a new observation. As before **all** observations satisfy one of the two hypotheses

$$H_0: \xi_1, \dots, \xi_t, \dots \sim \mathbb{P}_0$$


$$H_1: \xi_1, \dots, \xi_t, \dots \sim \mathbb{P}_1$$

Only now we like to reach a decision **as soon as possible**.

We first need a **Stopping rule**  $T(\xi_1, \dots, \xi_t)$  which at every time instant  $t$  consults the available information  $\xi_1, \dots, \xi_t$  and decides whether this information is *adequate to make a reliable decision between the two hypotheses or not*.

If YES, **Stop** and use **Decision rule**  $D(\xi_1, \dots, \xi_T) \in \{0, 1\}$

If NO, **ask for one more sample**



We expect, in the average, to need **(significantly) less samples** to reach a decision as compared to the conventional fixed sample size method, for the same level of confidence.

## The SPRT test (Wald 1947)

$$u_t = \log \left( \frac{d\mathbb{P}_1}{d\mathbb{P}_0}(\xi_1, \dots, \xi_t) \right)$$

We define **two** thresholds  $A < 0 < B$

Stopping rule:  $T = \inf_t \{t : u_t \notin (A, B)\}$

Decision rule:  $D(\xi_1, \dots, \xi_T) = \begin{cases} 1 & \text{if } u_T \geq B \\ 0 & \text{if } u_T \leq A \end{cases}$

Decision in favor of  $\mathbb{H}_1$

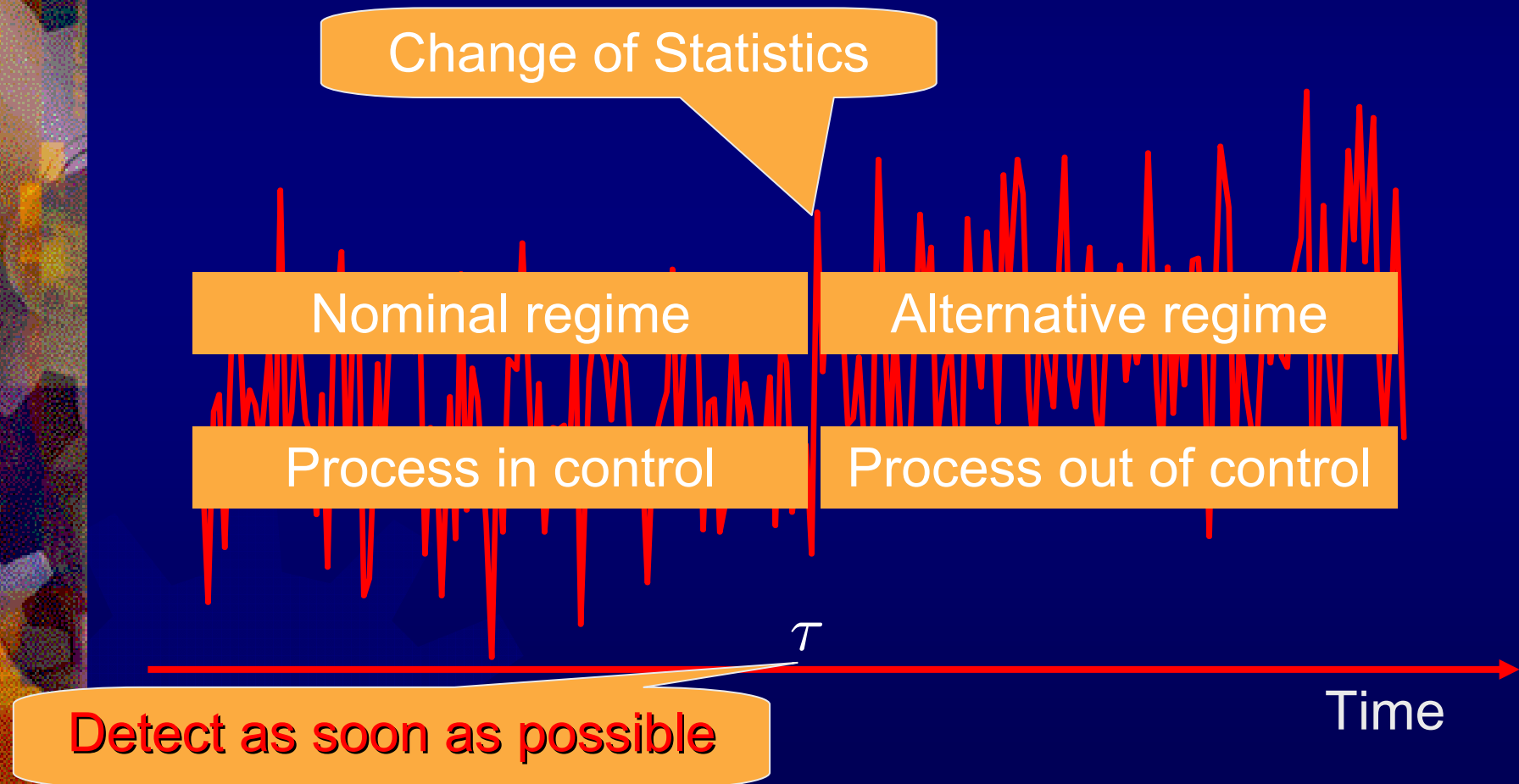
$B$



Optimum for i.i.d. observations (Wald and Wolfowitz, 1948); for BM with constant drift (Shiryayev, 1967) and for homogeneous Poisson (Peskir, Shiryayev, 2000).

# The Sequential change detection problem

Also known as the Disorder problem or the Change-Point problem or the Quickest Detection problem.





# Applications

Monitoring of quality of manufacturing process (1930's)

Biomedical Engineering

Electronic Communications

Econometrics

Seismology

Speech & Image Processing

Vibration monitoring

Security monitoring (fraud detection)

Spectrum monitoring

Scene monitoring

Network monitoring and diagnostics (router failures, intruder detection)

Databases .....



## Mathematical setup

We are observing sequentially a process  $\{\xi_t\}$  with the following statistics:

$$\begin{aligned}\xi_t &\sim \mathbb{P}_\infty && \text{for } 0 < t \leq \tau \\ &\sim \mathbb{P}_0 && \text{for } \tau < t\end{aligned}$$

**Goal:** Detect the change time  $\tau$  “as soon as possible”

- ★ Change time  $\tau$ : **deterministic (but unknown)**  
or **random**
- ★ Probability measures  $\mathbb{P}_\infty, \mathbb{P}_0$ : **known**



The observation process  $\{\xi_t\}$  is available sequentially.  
This can be expressed through the filtration  $\{\mathcal{F}_t\}$

$$\mathcal{F}_t = \sigma\{\xi_s : 0 < s \leq t\}.$$

- ★ Interested in **sequential detection schemes**.  
*At every time instant  $t$  we perform a test to decide whether to stop and declare an alarm or continue sampling. The test at time  $t$  must be based on the available information up to time  $t$ .*
- ★ Any sequential detection scheme can be represented by a **stopping time**  $T$  adapted to the filtration  $\{\mathcal{F}_t\}$

# Overview of existing results



$\mathbb{P}_\tau$  : the probability measure induced, when the change takes place at time  $\tau$

$\mathbb{E}_\tau[\cdot]$  : the corresponding expectation

$\mathbb{P}_\infty$  : all data under nominal regime

$\mathbb{P}_0$  : all data under alternative regime

## Optimality criteria

They must take into account two quantities:

- The detection delay  $T - \tau$
- The frequency of false alarms

Possible approaches: **Baysian and Min-max**



## **Bayesian approach** (Shiryayev 1978)

The change time  $\tau$  is random with exponential prior.

$$\text{Pro}[\tau = t] = (1 - \varpi) \varpi^t$$


For any stopping time  $T$  define the criterion:

$$J(T) = c \mathbb{E}[(T - \tau)^+] + \mathbb{P}[T \leq \tau]$$

**Optimization problem:**  $\inf_T J(T)$

Define the statistics:  $\pi_t = \mathbb{P}[\tau \leq t \mid \mathcal{F}_t]$

Stopping rule:  $T_S = \inf_t \{ t : \pi_t \geq \nu \}$

- 
- Discrete time: when  $\{\xi_t\}$  is i.i.d. and there is a change in the pdf from  $f_\infty(\xi)$  to  $f_0(\xi)$ .

$$\pi_t = \frac{\pi_{t-1} f_0(\xi_t)}{\pi_{t-1} f_0(\xi_t) + (1 - \pi_{t-1}) f_\infty(\xi_t)}$$

- Continuous time: when  $\{\xi_t\}$  is a Brownian Motion and there is a change in the constant drift from  $\mu_\infty$  to  $\mu_0$ .

## Min-max approach (Pollak, 1985)

The change time  $\tau$  is deterministic but unknown.

For any stopping time  $T$  define the criterion:

$$J(T) = \sup_{\tau} \mathbb{E}_{\tau} [ (T - \tau)^+ \mid T > \tau ]$$

**Optimization problem:**  $\inf_T J(T);$   
subject to:  $\mathbb{E}_{\infty} [ T ] \geq \gamma$

Discrete time: when  $\{\xi_t\}$  is i.i.d. and there is a change in the pdf from  $f_{\infty}(\xi)$  to  $f_0(\xi)$ .

Compute the statistics:  $S_t = (S_{t-1} + 1) \frac{f_0(\xi_n)}{f_{\infty}(\xi_n)}$ .

Stopping rule:  $T_P = \inf_t \{ t: S_t \geq \nu \}$  Mei (2006)

# CUSUM test and Lorden's criterion

Page (1954) introduced CUSUM for i.i.d. observations.

Suppose we are given  $\xi_1, \dots, \xi_t$ . Form a likelihood ratio test for the following two hypotheses:

$\mathbb{H}_0$ : All observations are under the nominal regime

$\mathbb{H}_1$ : There is a change at  $\tau < t$

assuming  $\tau$  known

$$\sup_{0 \leq \tau \leq t} \sum_{n=\tau+1}^t \log\left(\frac{f_0(\xi_n)}{f_\infty(\xi_n)}\right) \geq \nu$$

$$\sum_{n=1}^t \log\left(\frac{f_0(\xi_n)}{f_\infty(\xi_n)}\right) - \inf_{0 \leq \tau \leq t} \sum_{n=1}^{\tau} \log\left(\frac{f_0(\xi_n)}{f_\infty(\xi_n)}\right) \geq \nu$$



Define the CUSUM process  $y_t$  as follows:

$$y_t = u_t - m_t$$

where

$$u_t = \log\left(\frac{d\mathbb{P}_0}{d\mathbb{P}_\infty}(\mathcal{F}_t)\right)$$

$$m_t = \inf_{0 \leq s \leq t} u_s .$$

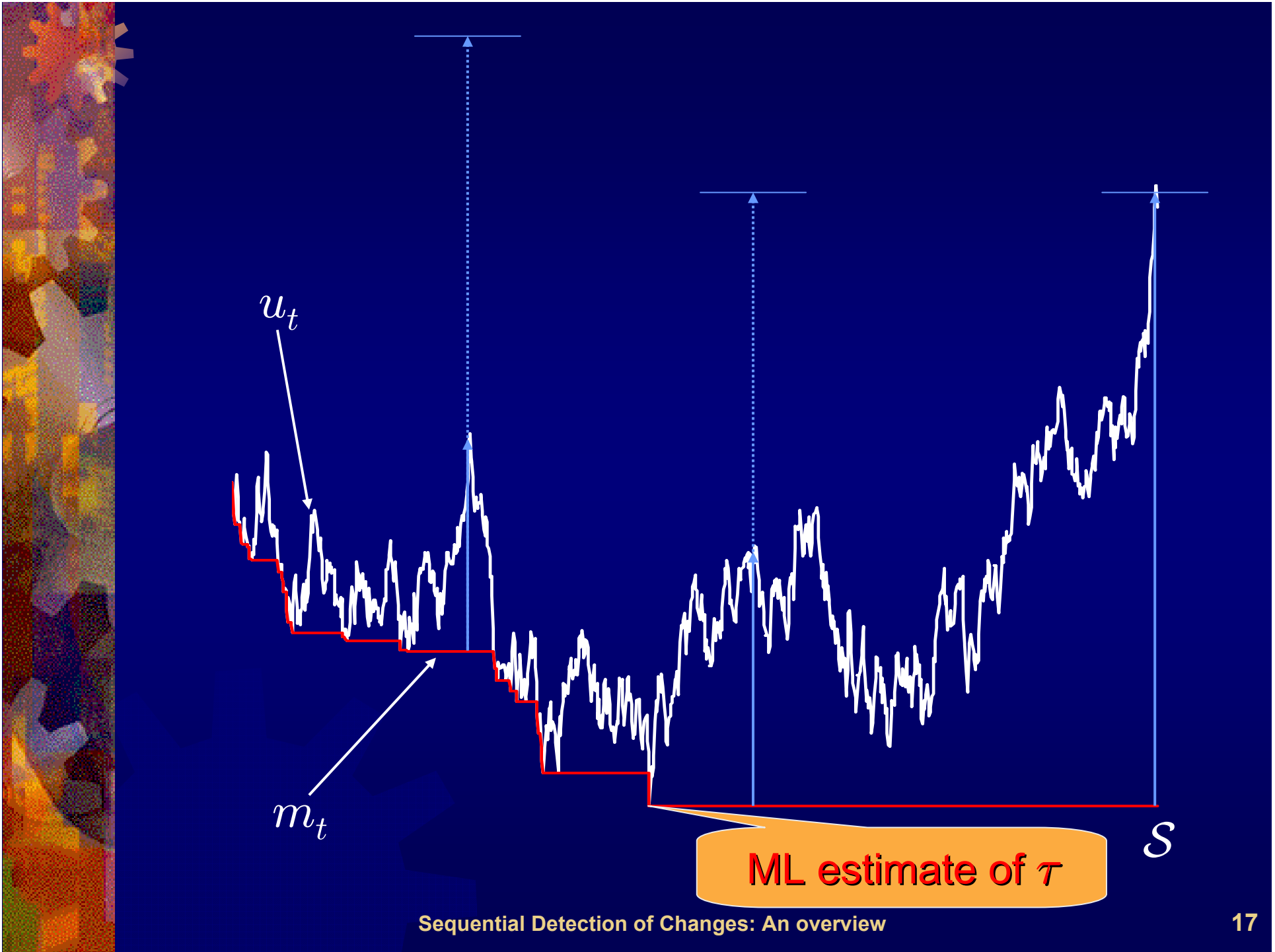
The CUSUM stopping time:

$$\mathcal{S} = \inf_t \{ t: y_t \geq \nu \}$$

For the i.i.d. case we have a convenient recursion:

$$y_t = \left( y_{t-1} + \log\left(\frac{f_0(\xi_t)}{f_\infty(\xi_t)}\right) \right)^+$$







Min-max criterion (Lorden 1971):

$$J(T) = \sup_{\tau} \text{esssup} \mathbb{E}_{\tau} [ (T - \tau)^+ | \mathcal{F}_{\tau} ]$$

**Optimization problem:**  $\inf_T J(T);$   
subject to:  $\mathbb{E}_{\infty} [ T ] \geq \gamma .$

- Lorden (1971) proved asymptotic optimality in discrete time for i.i.d. before and after the change for  $\gamma \rightarrow \infty$ .
- Discrete time: when  $\{\xi_t\}$  is i.i.d. before and after the change (Moustakides 1986, Ritov 1990).
- Continuous time: when  $\{\xi_t\}$  is a Brownian Motion with constant drift before and after the change (Shiryayev 1996, Beibel 1996).



## Course-layout

- ✦ Elements of optimal stopping (M 05/21)
- ✦ The SPRT test for i.i.d. and BM (W 05/23)

## Sequential Detection of Changes

- ✦ Change-time models and comparison of criteria (M 05/28)
- ✦ CUSUM for BM (W 05/30)
- ✦ Shiriyayev for BM and CUSUM for Ito process (M 06/04)
- ✦ CUSUM for Poisson (W 06/06)
- ✦ CUSUM for i.i.d. (M 06/11)
- ✦ Alternative Lorden-like criteria (W 06/13)&(M 06/18)
- ✦ Two sided CUSUM tests (W 06/20)