



Sequential techniques
for
**Hypothesis testing & Change
detection**

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Outline

- ★ Sequential hypothesis testing
- ★ The Sequential Probability Ratio Test (SPRT) for optimum hypothesis testing
- ★ Intrusion detection in wireless networks
- ★ Sequential change detection
- ★ Performance criteria and optimum detection rules
- ★ Lorden's criterion and the CUSUM test
- ★ Decentralized detection of changes



Sequential hypothesis testing

Conventional binary hypothesis testing (fixed sample size): Collection of observations ξ_1, \dots, ξ_K

$$\mathbb{H}_0: \xi_1, \dots, \xi_K \sim f_0(\xi_1, \dots, \xi_K);$$

$$\mathbb{H}_1: \xi_1, \dots, \xi_K \sim f_1(\xi_1, \dots, \xi_K);$$

Decision rule $D(\xi_1, \dots, \xi_K) \in \{0, 1\}$

$\mathbb{P}(D=1 \mid \mathbb{H}_1)$ (Correct decision)

$\mathbb{P}(D=1 \mid \mathbb{H}_0)$ (Type I error)

$\mathbb{P}(D=0 \mid \mathbb{H}_1)$ (Type II error)

$\mathbb{P}(D=0 \mid \mathbb{H}_0)$ (Correct decision)

Bayes formulation

$$\text{Pr. Err.}(D) = \mathbb{P}(\mathbb{H}_0)\mathbb{P}(D=1|\mathbb{H}_0) + \mathbb{P}(\mathbb{H}_1)\mathbb{P}(D=0|\mathbb{H}_1)$$

$$\min_D \text{Pr. Err.}(D)$$

Neyman-Pearson formulation

$$\max_D \mathbb{P}(D=1|\mathbb{H}_1) \quad \text{subject to } \mathbb{P}(D=1|\mathbb{H}_0) \leq \alpha$$

Likelihood ratio test:

$$\frac{f_1(\xi_1, \dots, \xi_K)}{f_0(\xi_1, \dots, \xi_K)} \underset{\mathbb{H}_0}{\overset{\mathbb{H}_1}{\gtrless}} \gamma$$

$$\text{For i.i.d.: } u_K = \sum_{n=1}^K \log \left(\frac{f_1(\xi_n)}{f_0(\xi_n)} \right) \underset{\mathbb{H}_0}{\overset{\mathbb{H}_1}{\gtrless}} \log(\gamma) = \gamma'$$

Sequential binary hypothesis testing

Observations $\xi_1, \dots, \xi_t, \dots$ are supplied **sequentially**.

$$\mathbb{H}_0: \xi_1, \dots, \xi_t, \dots \sim f_0(\xi_1, \dots, \xi_t, \dots)$$

$$\mathbb{H}_1: \xi_1, \dots, \xi_t, \dots \sim f_1(\xi_1, \dots, \xi_t, \dots)$$

Time	Observations	
1	ξ_1	$D(\xi_1)$
2	ξ_1, ξ_2	$D(\xi_1, \xi_2)$
...
t	ξ_1, \dots, ξ_t	$D(\xi_1, \dots, \xi_t)$
...

Decide reliably **as soon as possible**.

We apply a two-rule scheme:

1st Rule

Time Observations

1

ξ_1

2

ξ_1, ξ_2

...

...

T

ξ_1, \dots, ξ_T

Can ξ_1 make a reliable decision?

$$T(\xi_1, \dots, \xi_t) = \{\text{stop}, \text{continue}\}$$

Time T is
RANDOM

We **stop** receiving observations

2nd Rule

Decision Rule

$$D(\xi_1, \dots, \xi_T) \in \{0, 1\}$$

WHY sequential?

For the same level of confidence with a sequential test we need, in the average, **(significantly) less samples** than a fixed sample size test, to reach a decision.

The Sequential Probability Ratio Test (SPRT) (Wald 1947)

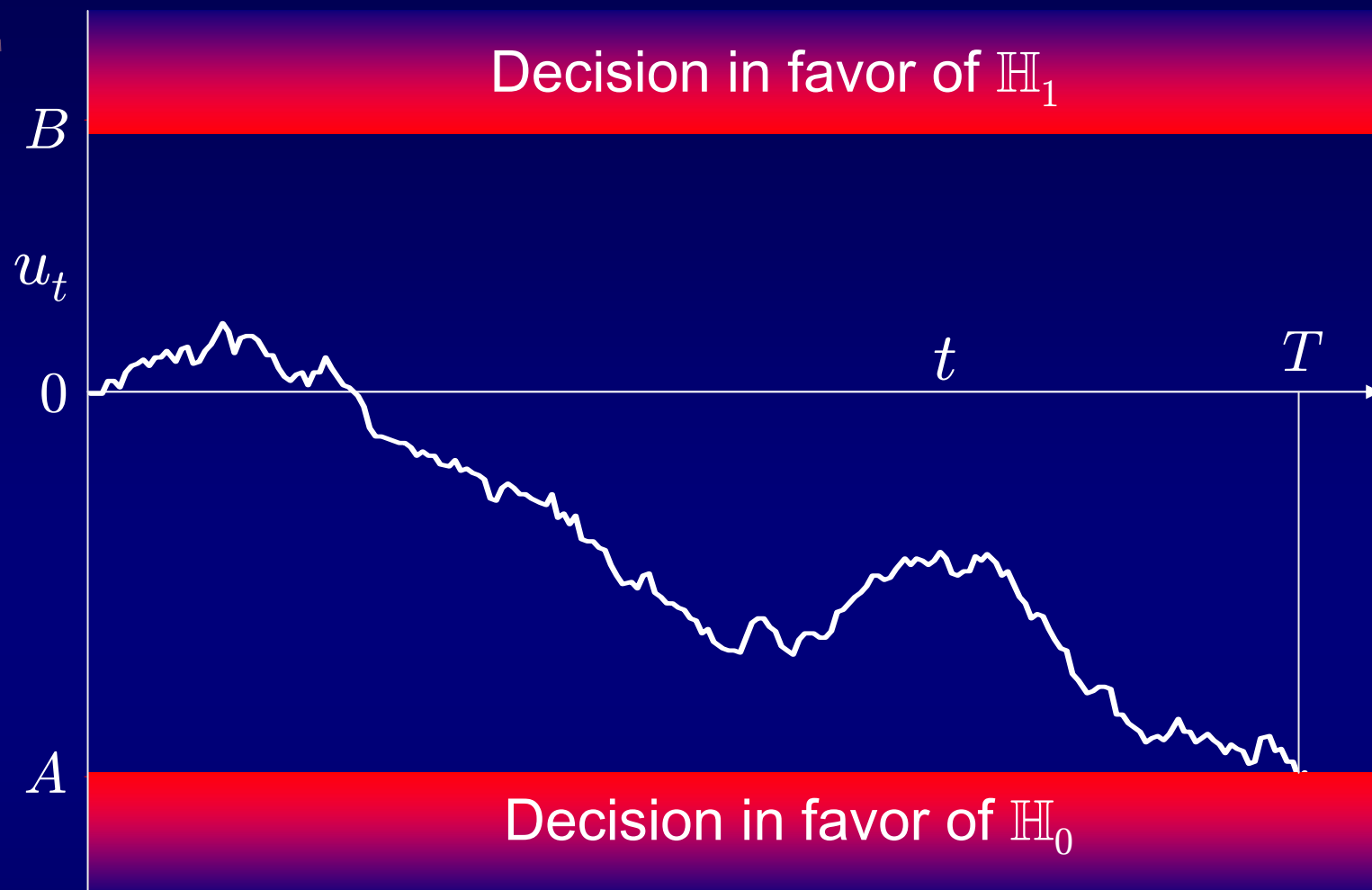
Changes with time

$$u_t = \log \left(\frac{f_1(\xi_1, \dots, \xi_t)}{f_0(\xi_1, \dots, \xi_t)} \right)$$

For i.i.d.

$$u_t = u_{t-1} + \log \left(\frac{f_1(\xi_t)}{f_0(\xi_t)} \right)$$

We define **two** thresholds $A < 0 < B$



Stopping rule: $T = \inf_t \{t : u_t \notin (A, B)\}$

Decision rule: $D(\xi_1, \dots, \xi_T) = \begin{cases} 1 & \text{if } u_T \geq B \\ 0 & \text{if } u_T \leq A \end{cases}$

Remarkable optimality property of SPRT

$$\min_{T,D} \mathbb{E}[T | H_0]$$

AND

$$\min_{T,D} \mathbb{E}[T | H_1]$$

subject to

$$\mathbb{P}[D_T = 1 | H_0] \leq \alpha; \quad \mathbb{P}[D_T = 0 | H_1] \leq \beta$$

- ★ Optimum for i.i.d. observations (Wald and Wolfowitz, 1948)
- ★ Brownian Motion with constant drift (Shiryayev, 1967)
- ★ Homogeneous Poisson (Peskir, Shiryayev, 2000)
- ★ **Open problems:** Dependent observations, multiple hypothesis testing




Misbehavior detection in wireless networks

(with Radosavac and Baras)

MAC Layer: When the channel is not in use, nodes wait a random (back-off) time and then reserve the channel.

- ✦ The node with the smaller back-off time reserves the channel first.
- ✦ Back-off times of legitimate nodes are distributed according to the **known** uniform distribution $f_0 = U[0, W]$.
- ✦ Attacker's goal is to reserve the channel more often than the legitimate users. Back-off distribution $f_1 = ?$ is **unknown**.

Use back-off time measurements to detect attacker!



For each node we measure **back-off times** (observations) sequentially and we decide whether it is legitimate (\mathbb{H}_0) or attacker (\mathbb{H}_1).

Candidate test: **SPRT**

Not directly applicable, since we don't know f_1

Quantification of an “attack”

N legitimate nodes have probability $1/N$ of reserving the channel.

A node is characterized as “attacker” if its probability of reserving the channel is **at least** η/N , where $\eta > 1$.

Example: $\eta = 1.1$ means that a node “attacks” if it reserves the channel 10% more than a legitimate node.

Probability of reserving the channel $\geq \eta/N$



$$\int_0^W x f_1(x) dx \leq \epsilon \frac{W}{2}$$

Defines a **CLASS**
 \mathcal{F} of possible
attack densities

where $\epsilon < 1$ a quantity that depends on η .

Optimization problem

$$\min_{T, D} \max_{f_1 \in \mathcal{F}} \mathbb{E}[T | \mathbb{H}_1] \quad \text{subject to}$$

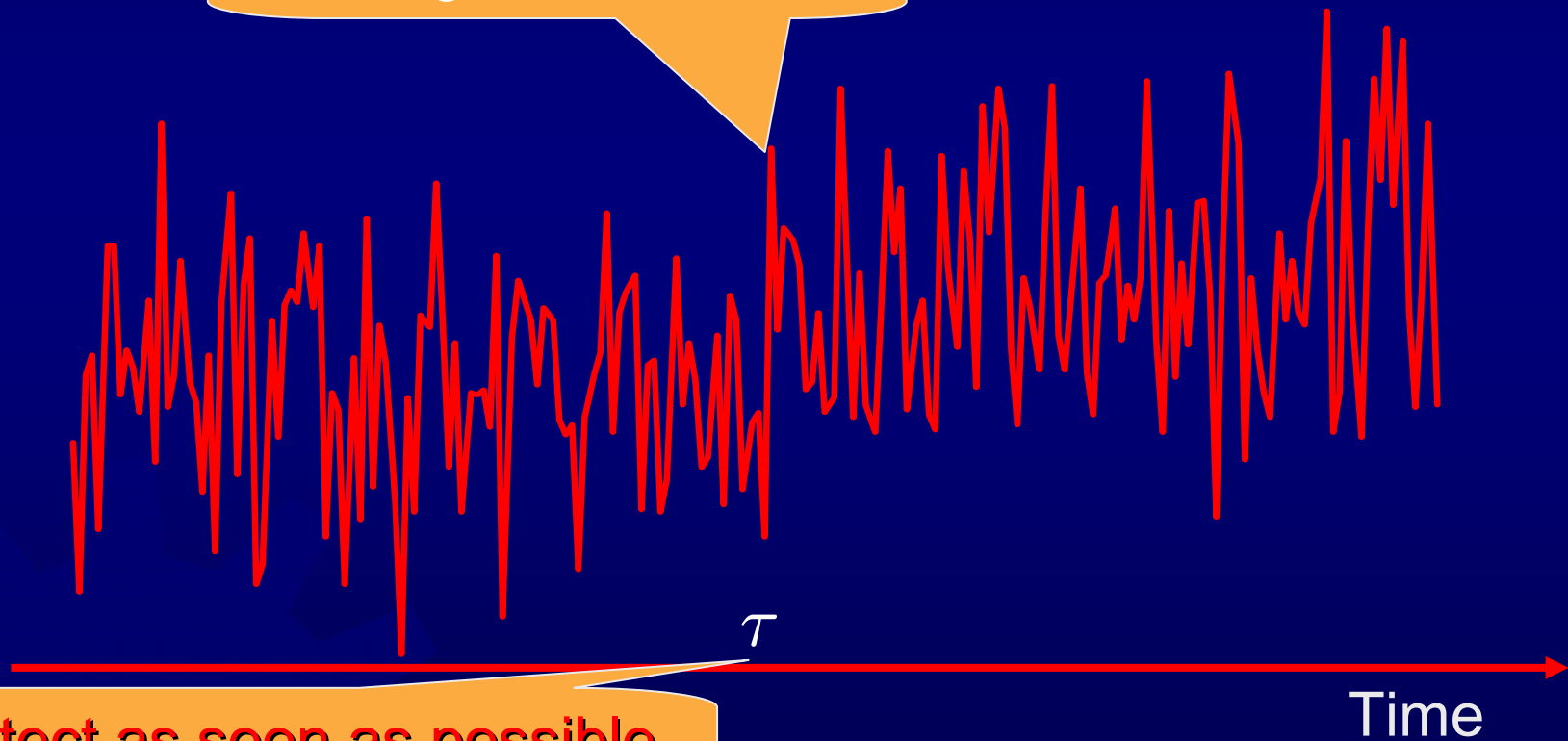
$$\mathbb{P}[D_T = 1 | \mathbb{H}_0] \leq \alpha; \quad \max_{f_1 \in \mathcal{F}} \mathbb{P}[D_T = 0 | \mathbb{H}_1] \leq \beta$$

$$\text{SPRT with } f_1^*(x) = \begin{cases} C e^{-\mu x} & 0 \leq x \leq W \\ 0 & x > W \end{cases}$$

The Sequential change detection problem

Also known as the **Disorder problem** or the **Change-Point problem** or the **Quickest Detection problem**.

Change of Statistics



Detect as soon as possible



Applications

Monitoring of quality of manufacturing process (1930's)

Biomedical Engineering

Electronic Communications

Econometrics

Seismology

Speech & Image Processing

Vibration monitoring

Security monitoring (fraud detection)

Spectrum monitoring

Scene monitoring

Network monitoring and diagnostics (router failures, intruder detection)

Databases



Mathematical setup

We are observing sequentially a process $\{\xi_t\}$ with the following statistics:

$$\begin{aligned}\xi_t &\sim f_0 && \text{for } 0 < t \leq \tau \\ &\sim f_1 && \text{for } \tau < t\end{aligned}$$

Goal: Detect the change time τ “as soon as possible”

- ★ Change time τ : **deterministic (but unknown)**
or **random**
- ★ Densities f_0, f_1 : **known**



The observation process $\{\xi_t\}$ is available sequentially.

Interested in **sequential detection schemes**.

- ✱ At every time instant t we perform a test to decide whether to stop (and issue an alarm) or continue sampling.
- ✱ The test at time t must be based on the **available information up to time t** (and not any future information).

Any sequential detection scheme is nothing but a **stopping rule T** that decides when to stop.



Overview of existing results

Optimality criteria

They must take into account two quantities:

- Detection delay $T - \tau$
- Frequency of false alarms

Possible approaches: Bayesian and Min-max

Bayesian approach (Shiryayev 1978)

The change time τ is random with geometric prior.

$$\text{Pro}[\tau = t] = (1 - \varpi) \varpi^t$$

For any stopping rule T define the criterion:

$$J(T) = c \mathbb{E}[(T - \tau)^+] + \mathbb{P}[T \leq \tau]$$



Optimization problem: $\inf_T J(T)$

Define the statistics: $\pi_t = \mathbb{P}[\tau \leq t \mid \xi_1, \dots, \xi_t]$

Stopping rule: $T_S = \inf_t \{ t: \pi_t \geq \nu \}$

- Discrete time: when $\{\xi_t\}$ is i.i.d. and there is a change in the pdf from $f_0(\xi)$ to $f_1(\xi)$.

$$\pi_t = \frac{\pi_{t-1} f_1(\xi_t)}{\pi_{t-1} f_1(\xi_t) + (1 - \pi_{t-1}) f_0(\xi_t)}$$

- Continuous time: when $\{\xi_t\}$ is a Brownian Motion and there is a change in the constant drift; or a Poisson process and there is a change in the constant rate.

Stochastic differential equation

Min-max approach (Pollak, 1985)

The change time τ is deterministic but unknown.

For any stopping rule T define the criterion:

$$J(T) = \sup_{\tau} \mathbb{E}_1[(T - \tau)^+ \mid T > \tau]$$

Optimization problem: $\inf_T J(T);$
subject to: $\mathbb{E}_0[T] \geq \gamma$

Discrete time: when $\{\xi_t\}$ is i.i.d. and there is a change in the pdf from $f_0(\xi)$ to $f_1(\xi)$.

Compute the statistics: $S_t = (S_{t-1} + 1) \frac{f_1(\xi_t)}{f_0(\xi_t)}$.

Stopping rule: $T_P = \inf_t \{ t: S_t \geq \nu \}$ Mei (2006)

CUSUM test and Lorden's criterion

Page (1954) introduced the CUmulative SUM (CUSUM) test for i.i.d. observations.

Suppose we are given ξ_1, \dots, ξ_t . Form a likelihood ratio test for the following two hypotheses:

\mathbb{H}_0 : All observations are under the nominal regime

\mathbb{H}_1 : There is a change at $\tau < t$

Assume τ **unknown**

$$\max_{0 \leq \tau \leq t} \sum_{n=\tau+1}^t \log \left(\frac{f_1(\xi_n)}{f_0(\xi_n)} \right) \underset{<}{\overset{\geq}{\equiv}} \nu$$

$$\sum_{n=1}^t \log \left(\frac{f_1(\xi_n)}{f_0(\xi_n)} \right) - \min_{0 \leq \tau \leq t} \sum_{n=1}^{\tau} \log \left(\frac{f_1(\xi_n)}{f_0(\xi_n)} \right) \underset{<}{\overset{\geq}{\equiv}} \nu$$



Define the CUSUM process y_t as follows:

$$y_t = u_t - m_t$$

where

$$u_t = \log \left(\frac{f_1(\xi_1, \dots, \xi_t)}{f_0(\xi_1, \dots, \xi_t)} \right)$$

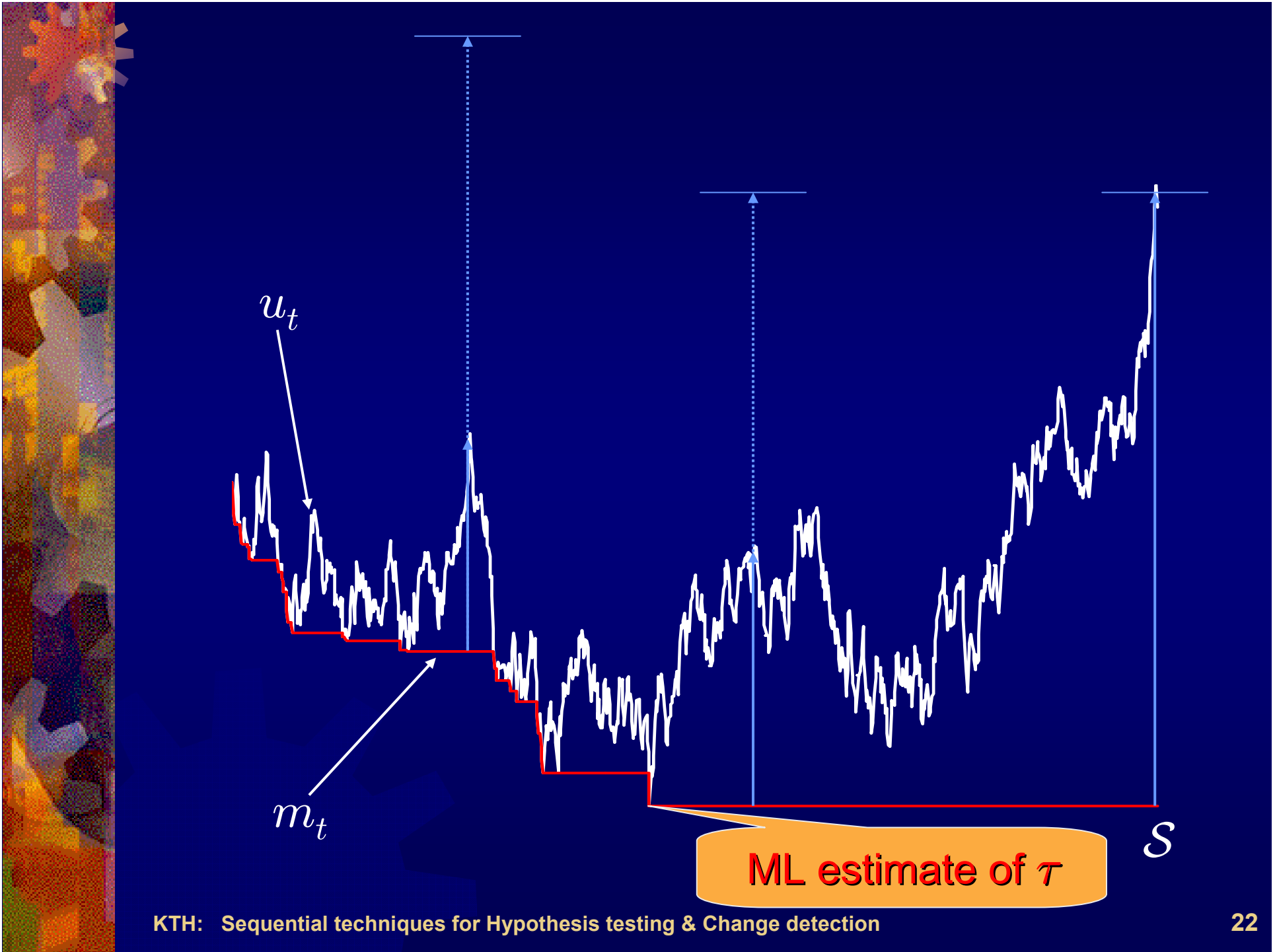
$$m_t = \inf_{0 \leq s \leq t} u_s .$$

The CUSUM stopping rule:

$$\mathcal{S} = \inf_t \{ t: y_t \geq \nu \}$$

For the i.i.d. case we have a convenient recursion:

$$y_t = \left(y_{t-1} + \log \left(\frac{f_1(\xi_t)}{f_0(\xi_t)} \right) \right)^+$$



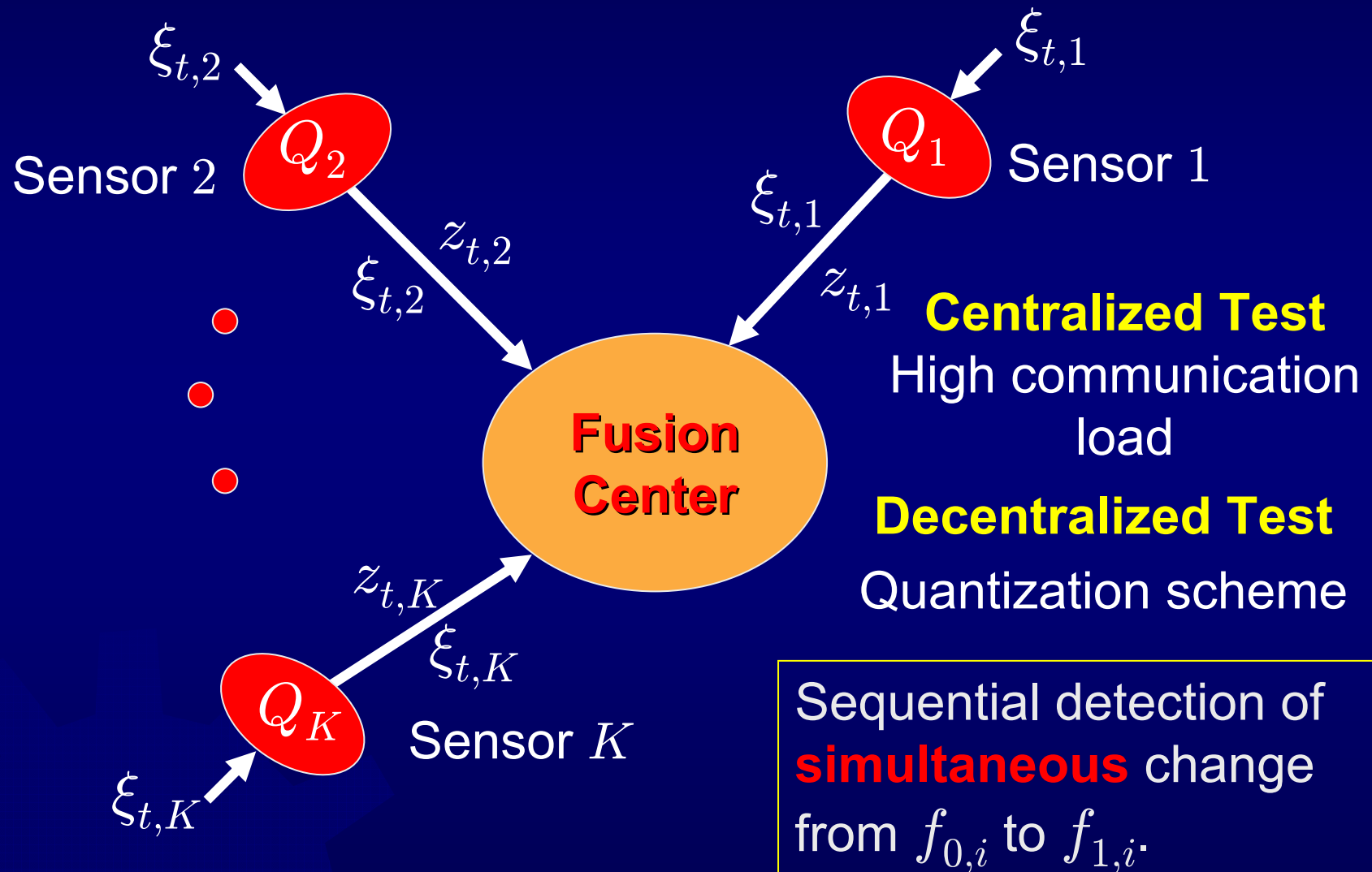
Min-max criterion (Lorden, 1971):

$$J(T) = \sup_{\tau} \sup_{\xi_1, \dots, \xi_{\tau}} \mathbb{E}_1[(T - \tau)^+ | \xi_1, \dots, \xi_{\tau}]$$

Optimization problem: $\inf_T J(T)$;
subject to: $\mathbb{E}_0[T] \geq \gamma$.

- ✱ For i.i.d. observations (Lorden, 1971), asymptotic optimality.
- ✱ For i.i.d. observations (Moustakides 1986 and Ritov 1990).
- ✱ Brownian Motion with constant drift (Shiryayev 1996, Beibel 1996). Ito processes (Moustakides 2004)
- ✱ Homogeneous Poisson (Moustakides, >2009)
- ✱ Change-time models and performance criteria (Moustakides 2008)
- ✱ **Open problems:** Dependency, multiple change possibilities

Decentralized change detection




$$J(Q, T) = \sup_T \sup_{\xi_1, \dots, \xi_T} \mathbb{E}_1[(T - \tau)^+ | \xi_1, \dots, \xi_T]$$

Optimization problem: $\inf_{Q, T} J(Q, T);$
subject to: $\mathbb{E}_0[T] \geq \gamma.$

For **given** $Q = \{Q_1, \dots, Q_K\}$ the optimum T is the CUSUM rule \mathcal{S}_Q that uses sequentially the sequence of quantized observation vectors $Z_t = [z_{t,1}, \dots, z_{t,K}]$. This leads to

$$J(Q, T) \geq J(Q, \mathcal{S}_Q) = J(Q)$$

Minimization over quantization: Based on methodology developed by Tsitsiklis (1993), Mei (2006) proved that

$$z_i = Q_i(\xi) = \begin{cases} 1 & \text{if } f_{1,i}(\xi)/f_{0,i}(\xi) \geq \lambda_i \\ 0 & \text{otherwise} \end{cases}$$



Using these quantizers, performance measure becomes a function of the quantization thresholds


$$J(\lambda_1, \dots, \lambda_K)$$

which must be minimized over the λ_i .

For any **given** combination of thresholds we have an **integral equation** satisfied by $J(\lambda_1, \dots, \lambda_K)$. Therefore, this function is well defined.

The optimum thresholds are obtained by performing the last minimization

NUMERICALLY!!!



THE END