

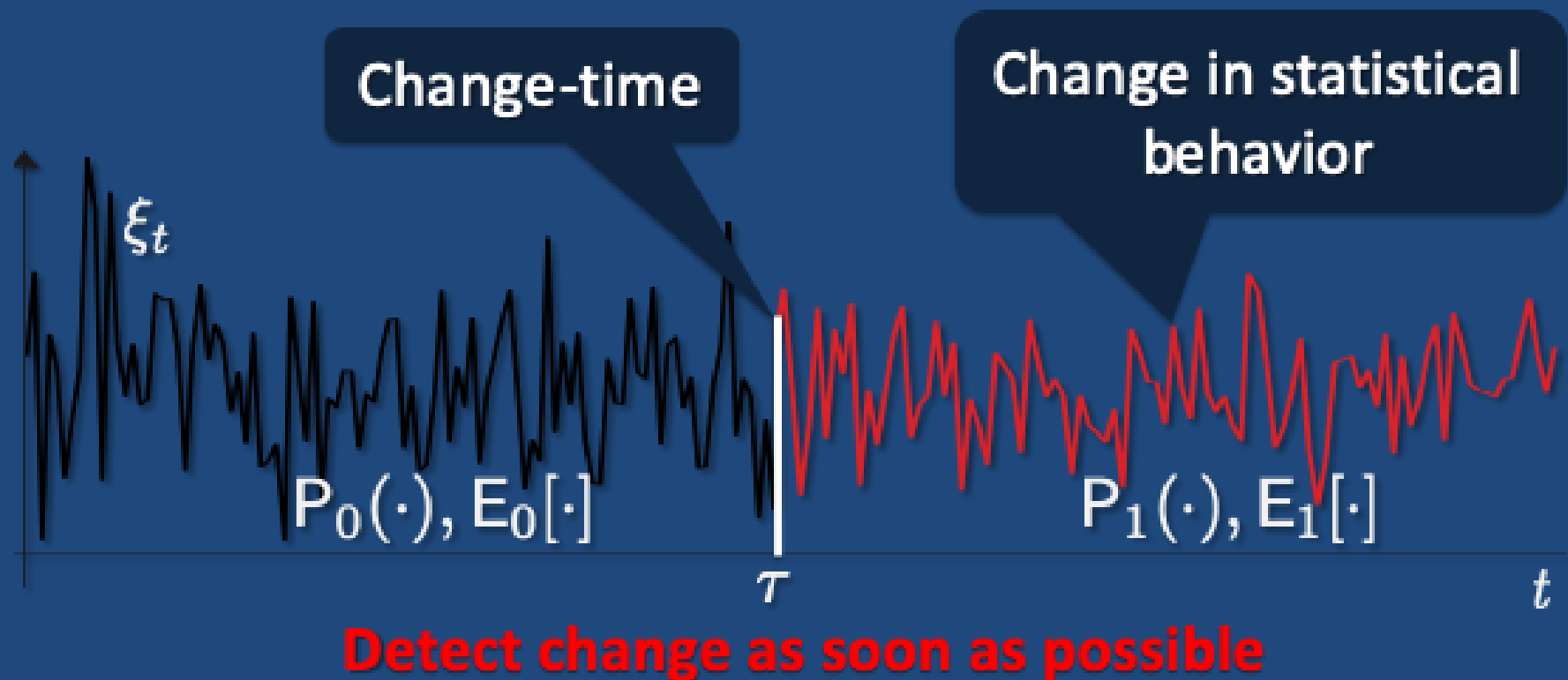
Quickest Detection of Changes

Formulations and Optimality Results

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Outline

- Problem definition
- Model for change mechanism
- Performance metrics
- Optimum detectors
- Decentralized formulations
- Data driven version



Data become available sequentially: at each time t obtain new sample ξ_t

Detector: Every instant t consult available data ξ_1, \dots, ξ_t decide if a change took place or not

1	ξ_1	Was there a change?	NO	Take more data (continue sampling)
2	ξ_1, ξ_2	Was there a change?	NO	
\vdots				
\vdots				
T	$\xi_1, \xi_2, \dots, \xi_T$	Was there a change?	YES	Stop (sampling)

Equivalently

t	$\xi_1, \xi_2, \dots, \xi_t$	Continue or Stop sampling
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Stopping rule

$$G_t(\xi_1, \dots, \xi_t)$$

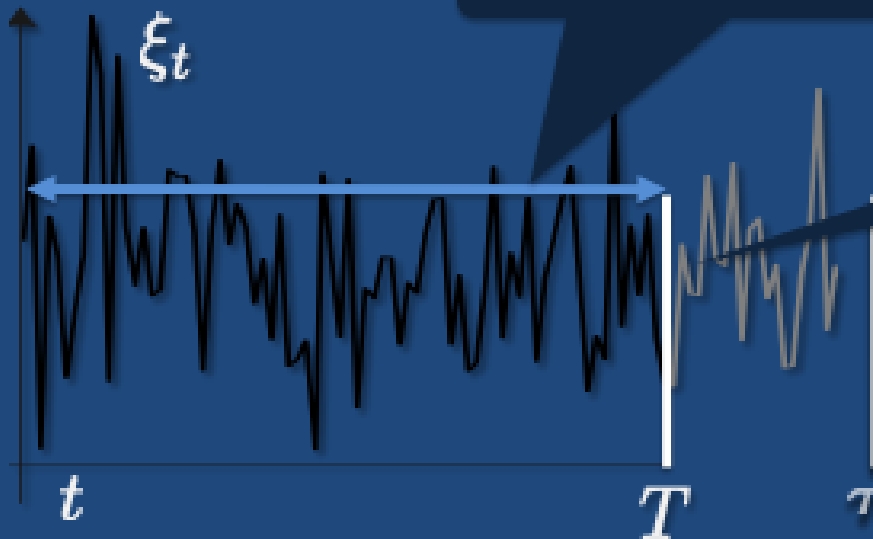
Stop
 \geq
 ν
 Continue

Stopping time

$$T = \inf_t \{G_t(\xi_1, \dots, \xi_t) \geq \nu\}$$

False Alarm

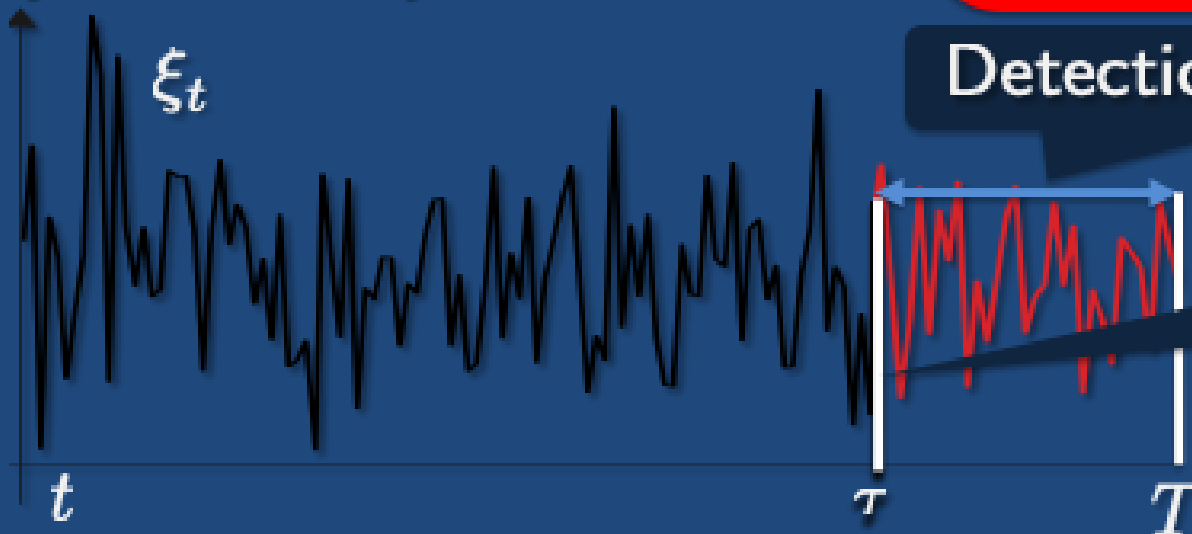
False Alarm Period



Probability of False Alarms

Design T to:
Minimize Detection Delay
or Maximize Detection
Probability, while controlling
False Alarms

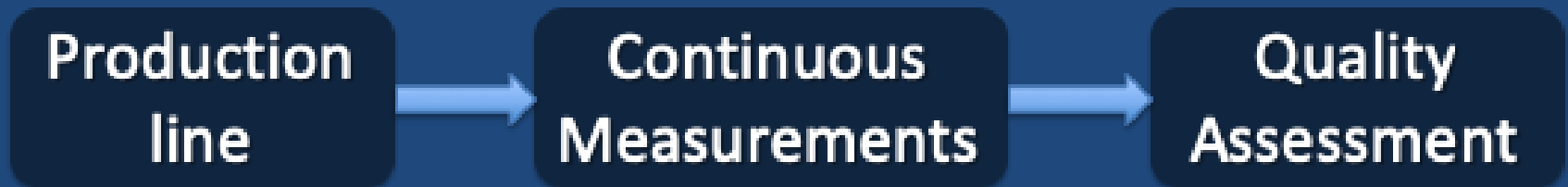
(Successful) Detection



Detection Delay $T - \tau$

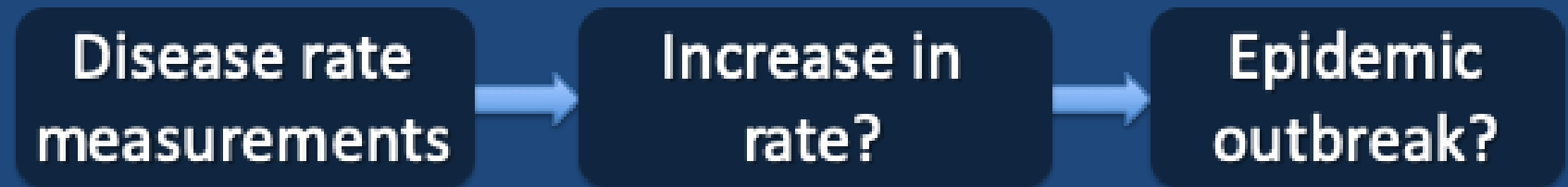
**Probability of
Detection**

Quality monitoring of manufacturing process

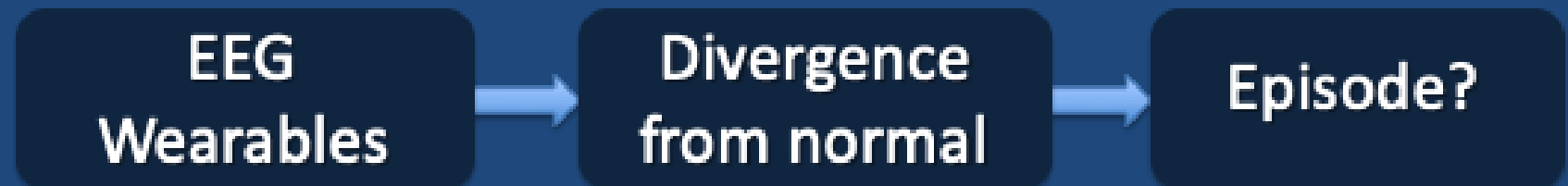


Medical Applications

Epidemic Detection



Early Detection of Epilepsy Episode



Financial Applications

- Structural Change-detection in Exchange Rates
- Portfolio Monitoring

Electronic Communications

Seismology

Speech & Image Processing (segmentation)

Vibration monitoring (Structural health monitoring)

Security monitoring (fraud detection)

Spectrum monitoring

Scene monitoring

Network monitoring (router failures, attack detection)

⋮



τ
Stopping
time

Dependent $\{X_t\}, \{\xi_t\}$

X_t : Vibrations at points of the structure

$\xi_t = AX_t + W_t$: Low dimensional noisy observations

If $\|X_t\|^2 \geq \nu$, then crack (**change** in structure)

Mechanism consults X_1, \dots, X_t and decides to apply **change (stop nominal behavior)** or not

Quickest detection of changes. May 2021, Toulouse, FRANCE.



Independent $\{X_t\}, \{\xi_t\}$

X_t : Coordinates of ball

ξ_t : Noisy sensor observations

If X_t inside the volume under the goal, “apply” change



At some point in time:
Attack!!!

Attacker no access to
observations...

$\{X_t\}, \{\xi_t\}$ independent

Change mechanism

Consults $\{X_t\}$ and controls stopping time τ

Scientist

Consults $\{\xi_t\}$ and controls stopping time T

Design T to detect τ asap

Detection Delay

$$\mathcal{J}(T) = E_1[T - \tau | T > \tau]$$

Hard Limited Delay

$$\mathcal{P}(T) = P_1(T \leq \tau + M | T > \tau)$$

If stopping rule used by change mechanism unknown
computation of $\mathcal{J}(T), \mathcal{P}(T)$ is not possible

We follow a **worst-case analysis**

Detection Delay

$$\mathcal{J}(T) = \sup_{\tau} E_1 [T - \tau | T > \tau]$$

Lorden (1971)

$$= \sup_{t > 0} \sup_{\xi_1, \dots, \xi_t} E_1 [T - t | T > t, \xi_1, \dots, \xi_t]$$

$$= \sup_{t > 0} E_1 [T - t | T > t] \text{ if } \{X_t\}, \{\xi_t\} \text{ independent}$$

Pollak (1985)

Hard Limited Delay

$$\mathcal{P}(T) = \inf_{\tau} P_1(T \leq \tau + M | T > \tau)$$

$$= \inf_{t > 0} \inf_{\xi_1, \dots, \xi_t} P_1(T \leq t + M | T > t, \xi_1, \dots, \xi_t)$$

$$= \inf_{t > 0} P_1(T \leq t + M | T > t) \text{ if } \{X_t\}, \{\xi_t\} \text{ independent}$$

Detection Delay

$$\inf_T \mathcal{J}(T) =$$
$$\inf_T \sup_{t>0} \sup_{\xi_1, \dots, \xi_t} E_1[T - t | T > t, \xi_1, \dots, \xi_t]$$

subject to : $E_0[T] \geq \gamma > 1$

Hard Limited Delay

$$\sup_T \mathcal{P}(T) =$$
$$\sup_T \inf_{t>0} \inf_{\xi_1, \dots, \xi_t} P_1(T \leq t + M | T > t, \xi_1, \dots, \xi_t)$$

subject to : $E_0[T] \geq \gamma > 1$

Shiryaev 1963



$\{\xi_t\}$ are i.i.d. before and after the change
with corresponding pdfs $f_0(\xi)$, $f_1(\xi)$

τ is independent from $\{\xi_t\}$ and follows a
geometric distribution $P(\tau = t) = p(1 - p)^t, t = 0, 1, \dots$

$$S_t = (1 + S_{t-1}) \frac{f_1(\xi_t)}{(1 - p)f_0(\xi_t)}$$

$$T_S = \inf_{t \geq 0} \{S_t \geq \nu\}$$

Threshold to satisfy false
alarm constraint with
equality

Lorden 1971

$\{\xi_t\}$ are i.i.d. before and after the change
with corresponding pdfs $f_0(\xi)$, $f_1(\xi)$

τ and $\{\xi_t\}$ are dependent



$$\inf_T \mathcal{J}(T) = \inf_T \sup_{t>0} \sup_{\xi_1, \dots, \xi_t} E_1[T - t | T > t, \xi_1, \dots, \xi_t]$$

subject to : $E_0[T] \geq \gamma > 1$

$S_t = \max\{S_{t-1}, 0\} + \log \frac{f_1(\xi_t)}{f_0(\xi_t)}$ Threshold to satisfy false
alarm constraint with
equality

$$T_C = \inf_{t>0} \{S_t \geq \nu\}$$

CUSUM test

CUSUM test $S_t = \max\{S_{t-1}, 0\} + \log \frac{f_1(\xi_t)}{f_0(\xi_t)}$

Known since 1954 as the **Page test**

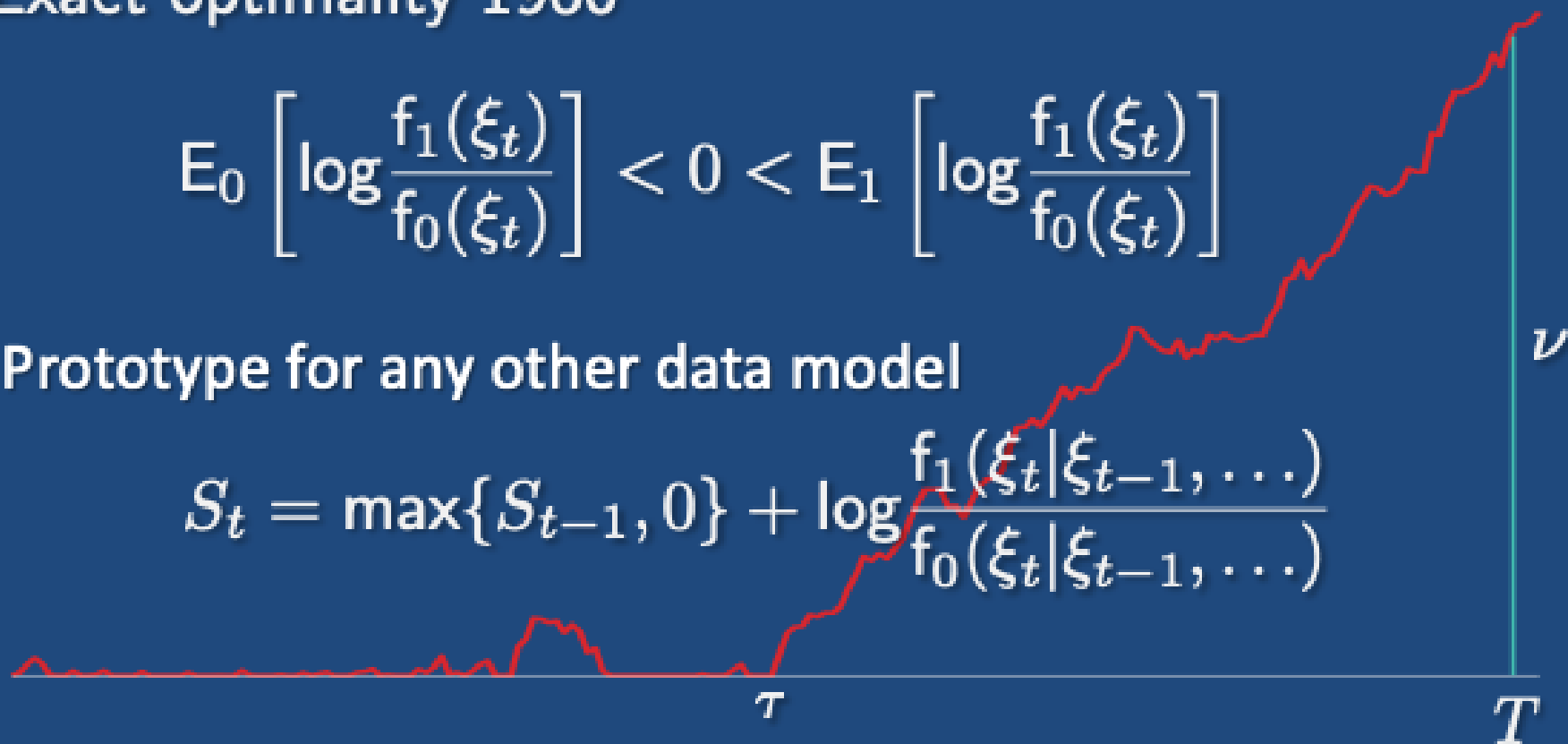
Asymptotic optimality ($\gamma \rightarrow \infty$) 1971

Exact optimality 1986

$$E_0 \left[\log \frac{f_1(\xi_t)}{f_0(\xi_t)} \right] < 0 < E_1 \left[\log \frac{f_1(\xi_t)}{f_0(\xi_t)} \right]$$

Prototype for any other data model

$$S_t = \max\{S_{t-1}, 0\} + \log \frac{f_1(\xi_t | \xi_{t-1}, \dots)}{f_0(\xi_t | \xi_{t-1}, \dots)}$$



$\{\xi_t\}$ Markov before and after the change with corresponding pdfs $f_0(\xi_t|\xi_{t-1})$, $f_1(\xi_t|\xi_{t-1})$

Conjecture

$$S_t = \max\{S_{t-1}, \phi(\xi_{t-1})\} + \log \frac{f_1(\xi_t|\xi_{t-1})}{f_0(\xi_t|\xi_{t-1})}$$

$$T_C = \inf_t \{S_t \geq \nu(\xi_t)\}$$

Functions $\phi(\xi)$, $\nu(\xi)$ are solution to a system of integral equations. Computed either numerically or asymptotically $\gamma \rightarrow \infty$

As $\gamma \rightarrow \infty$ we have $\phi(\xi) \rightarrow 0$ and $\nu(\xi) \rightarrow \nu$

Pollak 1985

$\{\xi_t\}$ are i.i.d. before and after the change
with corresponding pdfs $f_0(\xi)$, $f_1(\xi)$

τ and $\{\xi_t\}$ are independent

$$\inf_T \mathcal{J}(T) = \inf_T \sup_{t>0} E_1 [T - t | T > t]$$

subject to : $E_0[T] \geq \gamma > 1$

Shiryaev-Roberts-Pollak test

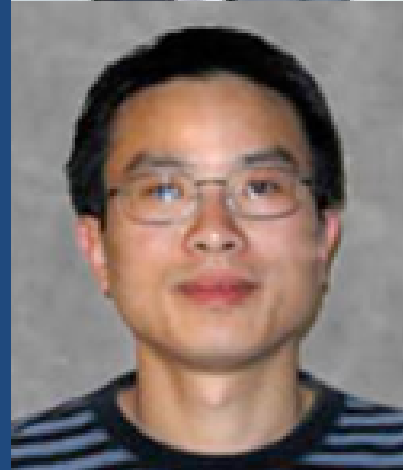
Mei 2006

$$S_t = (S_{t-1} + 1) \frac{f_1(\xi_t)}{f_0(\xi_t)} \quad T_{\text{SRP}} = \inf_t \{S_t \geq \nu\}$$

If S_0 specially designed T_{SRP} asymptotically
($\gamma \rightarrow \infty$) optimum.

Tartakovsky 2010

Exact optimality? 1997-2006



Tartakovsky 2019

τ and $\{\xi_t\}$ are independent

$$\inf_T \mathcal{J}(T) = \inf_T \sup_{t>0} E_1 [T - t | T > t]$$

subject to : $E_0[T] \geq \gamma > 1$



Multiple post-change possibilities. Data after change i.i.d. with pdf $f_1(\xi), \dots, f_k(\xi)$

$$S_t^i = (S_{t-1}^i + 1) \frac{f_i(\xi_t)}{f_0(\xi_t)}, \quad i = 1, \dots, k$$

$$T_T = \inf_{t>0} \{S_t^1 + \dots + S_t^k \geq \nu\}$$

T_T **asymptotically** ($\gamma \rightarrow \infty$) optimum

Hard Limited Delay

τ and $\{\xi_t\}$ are dependent

$$\sup_T \mathcal{P}(T) = \sup_T \inf_{t>0} \inf_{\xi_1, \dots, \xi_t} P_1(T \leq t + M | T > t, \xi_1, \dots, \xi_t)$$

subject to : $E_0[T] \geq \gamma > 1$

τ and $\{\xi_t\}$ are independent

$$\sup_T \mathcal{P}(T) = \sup_T \inf_{t>0} P_1(T \leq t + M | T > t)$$

subject to : $E_0[T] \geq \gamma > 1$

If $\{\xi_t\}$ are i.i.d. before and after the change with pdfs $f_0(\xi)$, $f_1(\xi)$, and interested in $M = 1$ (detect **immediately**)

$$T_{\text{Sh}} = \inf_{t>0} \left\{ \frac{f_1(\xi_t)}{f_0(\xi_t)} \geq \nu \right\}$$

Shewhart test
(1931)

Markovian pre- and post-change pdfs for observations

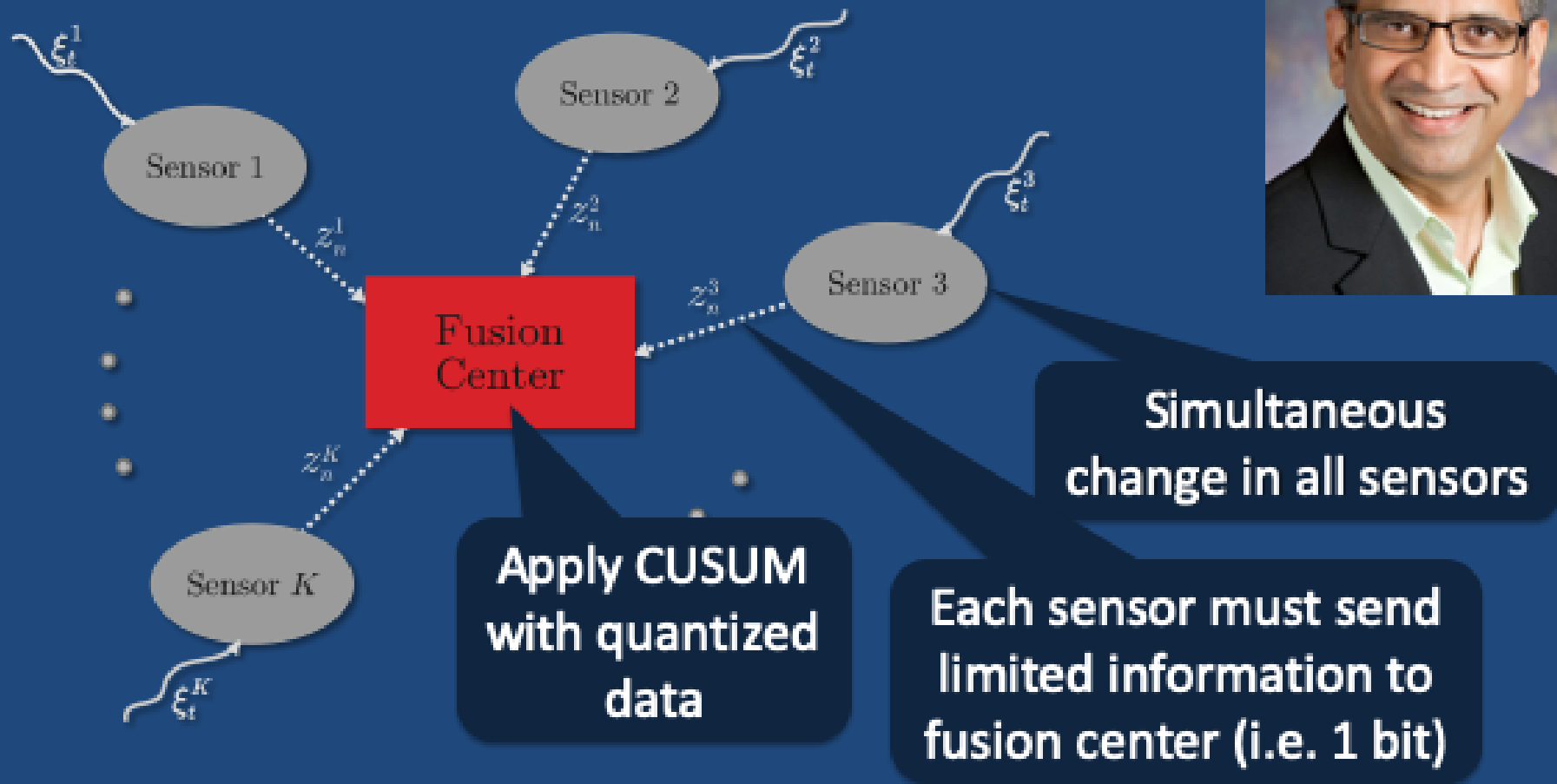
$$\sup_T \mathcal{P}(T) = \sup_T \inf_{t>0} \inf_{\xi_1, \dots, \xi_t} P_1(T = t + 1 | T > t, \xi_1, \dots, \xi_t)$$

subject to : $E_0[T] \geq \gamma > 1$

$$T_{\text{Sh}} = \inf_{t>0} \left\{ c(\xi_{t-1}) \frac{f_1(\xi_t | \xi_{t-1})}{f_0(\xi_t | \xi_{t-1})} \geq \nu(\xi_t) \right\}$$

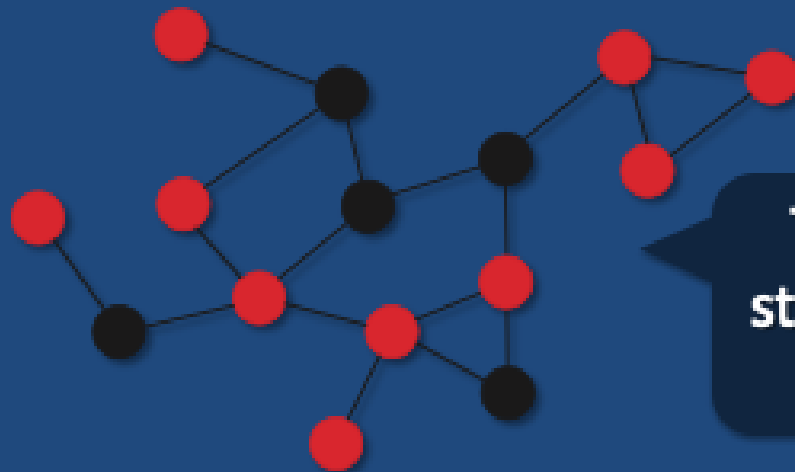
2015: Functions $c(\xi)$, $\nu(\xi)$ satisfy system of integral equation. Can be computed numerically or asymptotically ($\gamma \rightarrow \infty$). Simple solution for conditionally Gaussian: $\xi_t = \alpha(\xi_{t-1}) + w_t$ where $\{w_t\}$ i.i.d. $\mathcal{N}(0, 1)$

Veeravalli 2001



Veeravalli 2001: Apply optimum quantization on each likelihood ratio $\frac{f_1^i(\xi_t)}{f_0^i(\xi_t)}$

Mei 2011 - Fellouris 2016



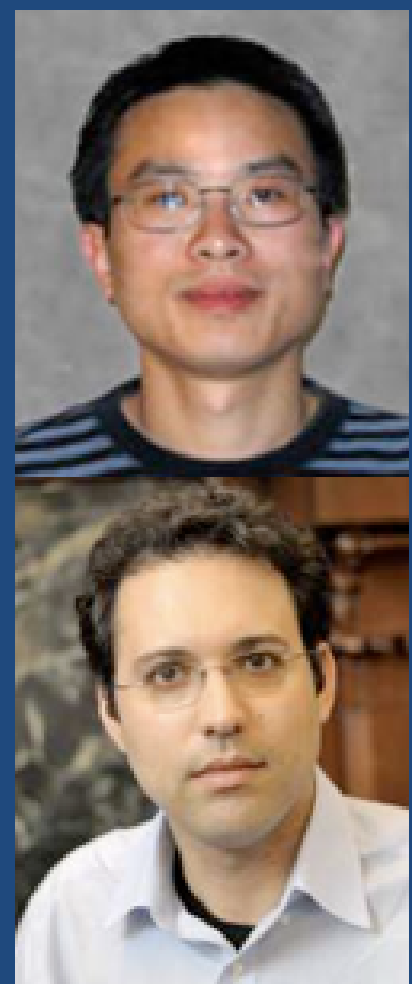
There is a change in statistical behavior of a **subgraph**.

$$S_t^i = \max\{S_{t-1}^i, 0\} + \log \frac{f_1^i(\xi_t)}{f_0^i(\xi_t)}$$

$$T = \inf_{t>0} \{\max_i S_t^i \geq \nu\}$$

$$T = \inf_{t>0} \{S_t^1 + \dots + S_t^K \geq \nu\}$$

$$T = \inf_{t>0} \left\{ \sum_{i=1}^K \log(1 - \pi + \pi e^{S_t^i}) \geq \nu \right\}$$



What if $f_0(\xi), f_1(\xi)$ **NOT known**

$\{\xi_1^0, \dots, \xi_N^0\}$ pre-change (training) data

$\{\xi_1^1, \dots, \xi_N^1\}$ post-change (training) data

Use data to
estimate $f_0(\xi), f_1(\xi)$

Density
estimation, not
very efficient

$$S_t = \max\{S_{t-1}, 0\} + \log \frac{f_1(\xi_t)}{f_0(\xi_t)}$$

Can we train a NN to estimate the $\log \frac{f_1(\xi_t)}{f_0(\xi_t)}$ using the training data ?

Need proper optimization problem!!!

Consider scalar functions $\phi(z), \psi(z)$ and scalar function $u(\xi)$. Define average cost:

$$\mathcal{J}(u) = E_0[\phi(u(\xi))] + E_1[\psi(u(\xi))]$$

If we want $\min_u \mathcal{J}(u)$ to yield

$$u(\xi) = \log \frac{f_1(\xi)}{f_0(\xi)}$$

it is necessary and sufficient

$$\psi'(u) = -e^{-u} \phi'(u)$$

$$\mathcal{J}(u) = \mathbb{E}_0[\phi(u(\xi))] + \mathbb{E}_1[\psi(u(\xi))]$$

Let $u(\xi, \theta)$ be the output of a NN with input ξ then

$$\hat{\mathcal{J}}(\theta) = \frac{1}{N} \sum_{l=1}^N \phi(u(\xi_l^0, \theta)) + \frac{1}{N} \sum_{l=1}^N \psi(u(\xi_l^1, \theta))$$

Optimize over θ (training)

$$\theta_t = \theta_{t-1} - \mu \left\{ \nabla_{\theta} \phi(u(\xi_t^0, \theta_{t-1})) + \nabla_{\theta} \psi(u(\xi_t^1, \theta_{t-1})) \right\} \rightarrow \theta_*$$

$$S_t = \max\{S_{t-1}, 0\} + u(\xi_t, \theta_*) \quad T_C = \inf_{t \geq 0} \{S_t \geq \nu\}$$

$$\xi_t = \begin{cases} \text{Before change : i.i.d. Gaussian} \\ \text{After change : } \text{sign}(\xi_{t-1})\sqrt{|\xi_{t-1}|} + w_t. \end{cases} \quad \log \frac{f_1(\xi_t|\xi_{t-1})}{f_0(\xi_t|\xi_{t-1})} = \log \frac{f_1(\xi_t, \xi_{t-1})}{f_0(\xi_t, \xi_{t-1})} - \log \frac{f_1(\xi_{t-1})}{f_0(\xi_{t-1})}$$

